

Bandwidth enhancement of a piezoelectric energy harvester using parametrically induced vibrations

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Abstract

A contemporary concept of externally coupling the vibration of a piezoelectric energy harvester with a parametrically excited beam to enhance the bandwidth of the whole system is presented in this paper. The proposed configuration not only serves in enhancing the bandwidth of operation of the harvester but also provides an option to utilize the configuration for a two directional planar vibrations case. This configuration adds a new approach to the extensive research being conducted worldwide in improving the versatility of the piezoelectric energy harvesters. The proposed configuration consists of two simple piezoelectric energy harvesters (made by attaching a macro fiber composite (MFC) patch on a substrate) with unimorph design and having tip masses with embedded cylindrical magnets. The beams are placed with the tip masses facing each other in an L-shaped configuration; when the main harvester is subject to a transverse vibration, the secondary harvester is subjected to a parametric vibration and vice versa if the directions are interchanged. The vibrating beams cause interaction between the magnetic tip masses inducing nonlinear magnetic coupling, thus modifying the linear behaviors. The magnetic tip mass of the parametrically vibrating beam induces changes in the stable equilibrium states of the whole system and also incorporates the off resonance peak due to parametrically induced resonance into the main harvester beam. In the experimental investigations aluminum and fiberglass substrates were used with varying substrate thickness and other variables like, size of the harvester, tip mass, distance between the harvester beams and base acceleration etc. were maintained constant. The whole experimental setup was subject to a frequency sweep in a range of 5-50Hz and the open circuit voltage data was obtained from the vibrating beams for both linear (no magnetic interaction) and nonlinear cases. The results obtained in this study are very promising in enhancing the bandwidth of operation of the piezoelectric energy harvesters and the concept can be extended to a case where in the vibrations from all three dimensions can be utilized in harvesting energy effectively.

1. INTRODUCTION

Harvesting energy from surroundings has been a prodding topic for mankind since ancient ages, the water wheel, the wind mills, the greenhouses etc. are a few early examples of energy harvesting for a large scale, in the past few decades enormous emphasis has been laid on the usage of renewable forms of energy

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[6]. Though these have primarily served the energy crisis for a larger scale of power production, there is a major scope for research in the domain of small scale energy harvesting in the order of 50mW and lower. With the emergence of low power electronics and sensor devices, a tremendous challenge has been conferred upon researchers to pack enough energy in the minimum available space, leading a revolution in battery technology [6-10]. But the major drawback of using batteries is the periodic replacement of the batteries for continued functioning of the electronics. This limitation has been addressed by the development of small scale energy harvesting techniques; the usage of electrostatic, electromagnetic, solar, piezoelectric etc. has provided a means to harness energy for low power systems on a long term basis [6-8]. Of the above mentioned methods piezoelectric energy harvesting (PEH) provides an added advantage of high power density for the given material volume [6].

Over the last decade, there has been substantial development in the realm of PEH; various designs were reported in the literature stating the added benefits of each design [6-10]. The initial harvester designs consisted of a transversely vibrating cantilever beam with a piezoelectric element attached at the root of the beam [6]. This was the simplest designs and had a major drawback owing to a narrow bandwidth of operational frequency. This was overcome by the introduction of magnets at the tip of the beam, L-shaped beam designs etc... [3,5,6,10] Researchers have even investigated the application of the basic cantilever designs for axial mode of vibrations, this results in a parametric vibration of the cantilever beam (the concepts of transverse and parametric vibrations of a PEH system have been presented in the succeeding sections) [1,2,4,7]. Thus, to further contribute to the effort of numerous researchers working in the area of widening the bandwidth of operation of energy harvesters, a contemporary design utilizing both the transverse and the parametric vibrations to enhance the bandwidth of a PEH system has been presented in this paper. The proposed design consists of a simple cantilever flexural member (main beam) undergoing transverse vibrations and a secondary cantilever flexural member (auxiliary beam) undergoing parametric vibration, the auxiliary beam subjects the system to an off resonance peak thereby enhancing the bandwidth of operation for the whole system.

This paper consists of five sections; the first section gives a brief introduction about energy harvesting and the various methods and means that were explored over the years. The second section deals with the concepts of transverse and parametric vibrations, and the lumped parameter equations available for each of these cases. The third section introduces the potential energy variation of the proposed system, giving an account of the formulation involved and the plots showing the variation of potential energy for different cases. The fourth section discusses the experimental investigation of the proposed system and the concurrent observations and their significance. The last section concludes the paper identifying the major contributions from the present study and presenting the key areas for future work.

2. TRANSVERSE AND PARAMETRIC VIBRATIONS

A brief overview of transverse and parametric vibrations has been discussed in this section. When an external excitation is applied out of the plane of beading for a flexural member, the member is subjected to a transverse vibration. Similarly, when an external excitation is applied along the axial direction of a flexural member, the member undergoes transverse instability at a frequency twice its modal frequencies and this is known as the *principle parametric resonance*; this was first reported by Faraday in 1831 and investigated by many researchers after that [2-4]. Fig. 1 shows the transverse and the parametric vibrations of a simple cantilever beam.

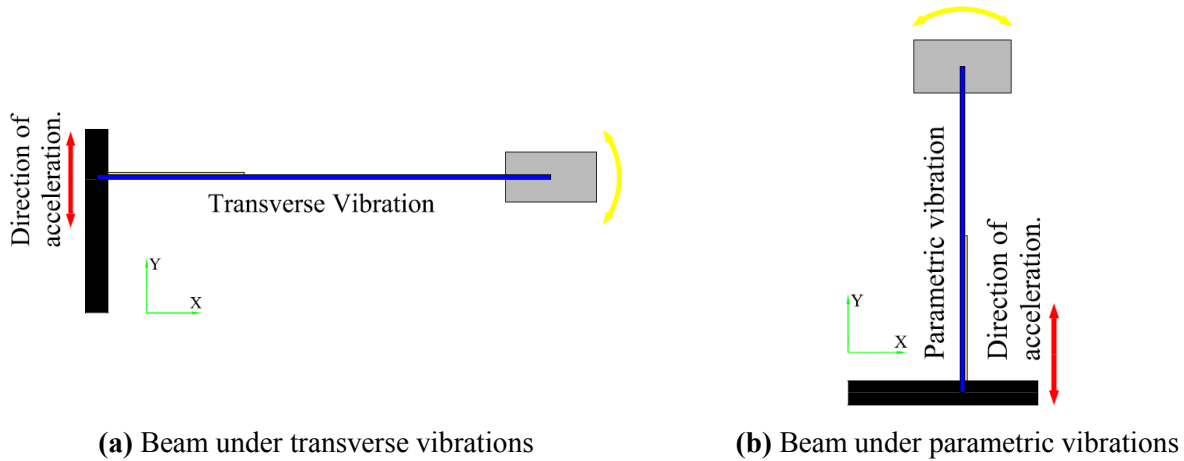


Figure 1. Layout of transverse and parametric vibrations

These vibrations have been studied in detail over the years and the mathematical expressions for a lumped parameter formulation for these vibrations are presented in eq. 1 and eq. 2 [6,4,7,10].

$$\ddot{\eta}_r(t) + 2\zeta_r \omega_r \dot{\eta}_r(t) + \omega_r^2 \eta_r(t) = -f_r \ddot{w}_b(t) \quad (1)$$

$$\text{Where, } w(x,t) = \sum_{r=1}^{\infty} \phi_r(x) \eta_r(t)$$

$$M_{eq} = \int_0^L m(x) (\phi_r(x))^2 dx + M_t (\phi_r(L))^2$$

$$K_{eq} = \int_0^L EI(x) (\phi_r''(x))^2 dx$$

$$F_{eq} = \int_0^L m(x) \phi_r(x) dx + M_t \phi_r(L)$$

$$K_{eq} = \omega_r^2 M_{eq}$$

$$C_{eq} = 2\zeta_r \omega_r M_{eq}$$

$$F_{eq} = f_r M_{eq}$$

In the above expression, $w(x,t)$ is the displacement of the beam in generalized co-ordinates, x being the horizontal axis and y the vertical axis. The displacement is represented as a summation of the modal co-ordinates ϕ and a function of time η , and r being the r^{th} mode of vibration. M_{eq} , K_{eq} , C_{eq} , F_{eq} are the equivalent modal mass, stiffness, damping and force respectively. E is the Young's modulus of the beam material, I is the moment of inertia of the beam cross section, m is the mass per unit length of the beam, M_t is tip mass and ω_r is the modal frequency of the r^{th} mode.

$$\ddot{u} + 2\mu_1 \dot{u} + \omega_n^2 u + \mu_2 |\dot{u}| \dot{u} + \alpha u^3 + 2\beta (u^2 \ddot{u} + u \dot{u}^2) = u \frac{F}{m_{eq}} \cos(\omega t) \quad (2)$$

In the above expression, $u(x,t)$ is the displacement of the beam in generalized co-ordinates in x direction and time t , μ_1 and μ_2 are the viscous and quadratic (air drag) damping terms respectively, α and β are constants and the terms containing them represent the cubic nonlinearities and inertial nonlinearities, m_{eq} is the equivalent mass of the system and, F and ω are the amplitude and excitation frequency of the forcing function, and ω_n represents the natural frequency of the system. It is interesting to note that, in the absence of the nonlinearities, quadratic damping term, and external forcing function, the equation reduces

to that of a free vibration case of a linear transverse vibrating member. Thus, the parametric vibration is caused due to the inherent nonlinearities in the member, and the presence of an external forcing function drives the flexural member into parametric resonance.

There are several mathematical techniques outlined in the literature for solving the expressions stated above, of these the perturbations techniques like method of multiple scales, harmonic balance are popularly used for parametric vibrations and frequency domain or time domain modal analysis methods are used for transverse vibrations [1,2,4,7].

3. POTENTIAL ENERGY DISTRIBUTION OF A COMBINED SYSTEM

The potential energy of a system of magnets can be expressed using many different formulations, for the present system the enhanced integral formulation will be used [9-11]. As the magnets play a vital role in determining the behavior of the present system in consideration, it is of utmost importance to use a good degree of accuracy in the formulation of the magnetic interaction in order to get a comprehensive picture of the effect of magnets on the proposed system, the conventional dipole equations do not provide a great degree of accuracy at close distances of the order of the size of the magnets [9,11]. Fig. 2 shows a typical representation of two magnets and the corresponding expressions are elucidated in Eq. 3.

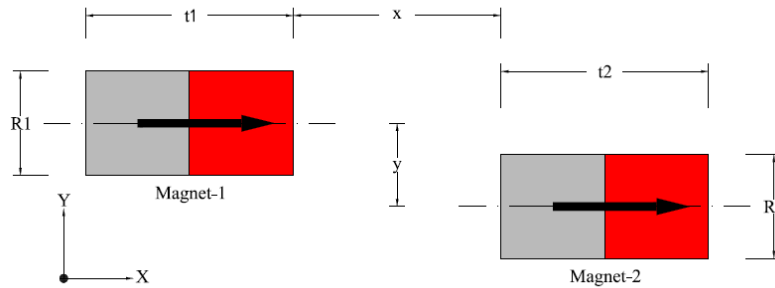


Figure 2. Representation of two magnets ‘x’ m and ‘y’ m axial and lateral separation respectively

$$E_{1-2}(x, y) = \varepsilon \mu_o M_1 M_2 \pi R_1 R_2^2 \int_0^\infty J_0\left(\frac{yq}{R_2}\right) \frac{J_1\left(\frac{R_1}{R_2} q\right)}{q^2} J_1(q) U(x, q) dq \quad (3)$$

$$\text{Where, } U(x, q) = \left[e^{\left(-2d_2 - x\right)\frac{q}{R_2}} + e^{\left(-2d_1 - x\right)\frac{q}{R_2}} - e^{\left(-2d_1 + 2d_2 + x\right)\frac{q}{R_2}} - e^{\left(-x\right)\frac{q}{R_2}} \right]$$

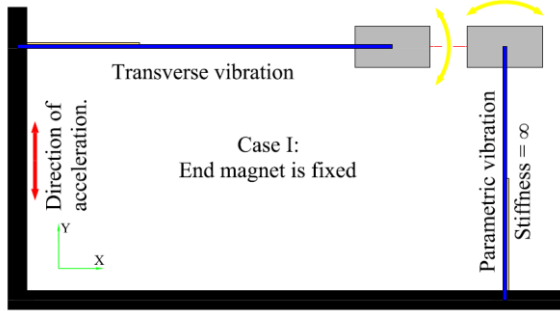
$$d_i = \frac{t_i}{2}, i = 1, 2$$

$$\varepsilon = \begin{pmatrix} +1 \text{ for attractive configuration} \\ -1 \text{ for repulsive configuration} \end{pmatrix}$$

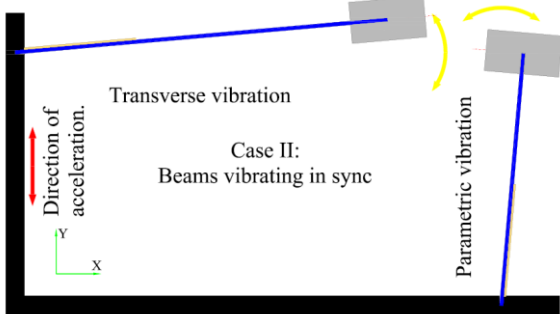
$$E_{Potential, beam} = \frac{1}{2} K_{eq} w^2(L, t) \quad (4)$$

$$E_{Potential} = \sum E_{Potential, beam} + E_{1-2}$$

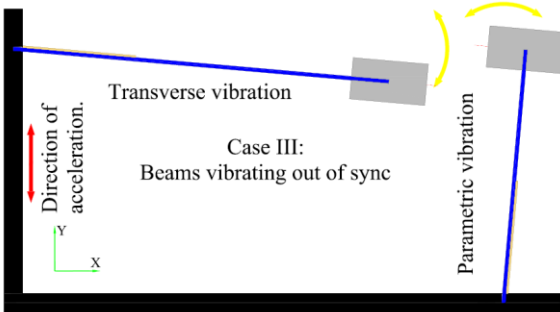
In the above expression, E_{1-2} is the magnetic interaction energy between the magnets 1 and 2; μ_o is the magnetic permeability of vacuum; M_1 and M_2 are the saturation magnetizations of magnets 1 and 2, respectively; R_1 and R_2 are the radii of the cylindrical magnets; J_0 and J_1 are the modified Bessel functions of the first type of order 0 and 1, respectively; y is the lateral separation between the magnetic axes, x is the axial separation between the end of the magnets, the Bessel functions of q define the shape of the magnets and t_i is the height of the cylindrical magnets. $E_{Potential,beam}$ is the potential energy of the beam expressed in terms of equivalent beam stiffness K_{eq} and the displacement of the tip of the beam $w(L,t)$. As there is no available solution for the integral in the magnetic interaction energy equation, it was solved numerically using MATLAB.



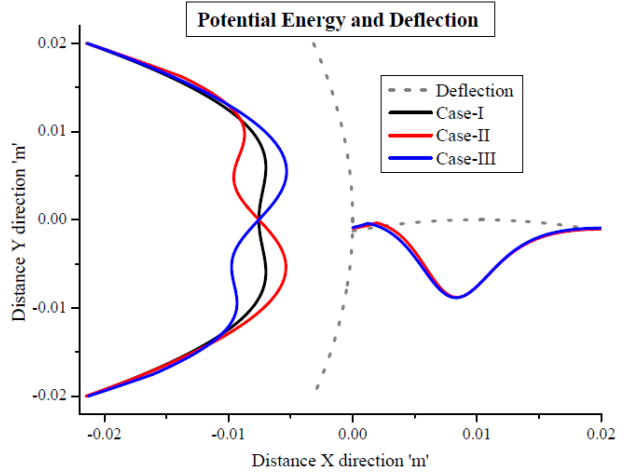
(a) Case I: When the auxiliary beam is fixed



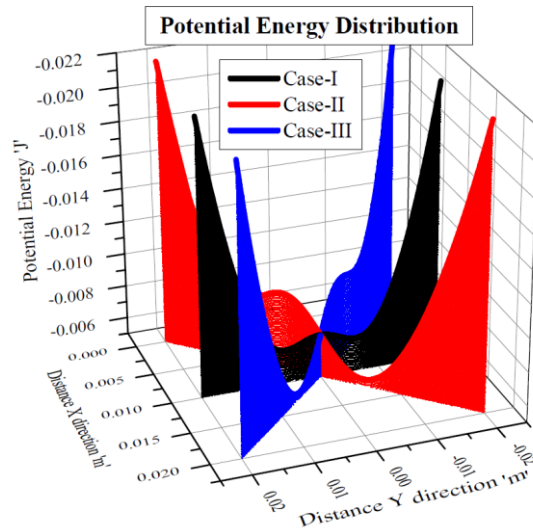
(b) Case II: Both the beams are in synchronized motion



(c) Case III: Both the beams are not in synchronized motion



(d) Potential energy distribution and deflection of the corresponding beams



(e) Potential energy distribution for the whole system for respective cases

Figure 3. (a) – (c) Layout of three possible scenarios of the system, (d) – (e) Representation of the potential energy distribution for the system.

The interaction energy of the magnets contributes to the potential energy of the whole system, for better representation of the effect of the magnets, a system consisting of two cantilever beams with

embedded tip masses facing each other as shown in fig. 3 is considered. For simplicity the potential energy of the beams resulting from the stiffness of the beam material and the interaction energy of the magnets is summated numerically as expressed in Eq. 4, and the resulting variation of potential energy at different positions of the tip masses are shown graphically. Moreover, the variation of potential energy for three possible cases of vibration is also enumerated for clear understanding. Case-I exhibits the situation when the magnet on the member undergoing parametric vibration i.e. the auxiliary beam is considered to be static and the member undergoing transverse vibration i.e. the main beam vibrates due to the external periodic force. Case-II deals with a situation where both the beams undergo vibration and the vibration of the beams is synchronized with respect to each other and Case-III portrays the situation where the vibration of the beams is completely out of sync. These three cases illustrate the possible extreme scenarios for the vibration of the beams, thus when the beams are subject to an external excitation, the potential energy distribution for the system is likely to fall in between the curves shown in fig. 3.

Based on the above discussion and Fig. 3, it is evident that the presence of the auxiliary beam which vibrates parametrically causes a change in the potential energy of the main beam and vice versa thus inducing nonlinearity into the system. This nonlinear variation of energy results in widening of the bandwidth of the output open circuit voltage (V_O) and output power (P_O) obtained from the vibration of the cantilever PEH system as discussed in the following section.

4. EXPERIMENTAL INVESTIGATION OF THE PROPOSED DESIGN

The proposed concept of enhancing the bandwidth of V_O and P_O of a linear cantilever PEH with the help of an externally vibrating cantilever beam undergoing parametric vibrations, and consisting of magnetic tip masses is discussed in this section.

The experimental setup consists of two beams placed perpendicular to each other as shown in fig. 4, the main beam was placed perpendicular to the direction of excitation and undergoes transverse vibrations; the auxiliary beam was placed parallel to the direction of excitation undergoing parametric vibration. MFC patches were attached to the root of the beams and the voltage produced was monitored using National Instruments (NI) Voltage DAQ card having an internal resistance of 1M Ω . In order to lower the natural frequencies and tune the first harmonic vibration, the beams were attached with tip masses. The tip masses were embedded with magnets thus inducing non-linearity into the system. The beams were supported on a frame which was in turn fixed to the moving arm of the shaker. The whole experimental setup for both linear case and nonlinear case is as shown in fig. 5.

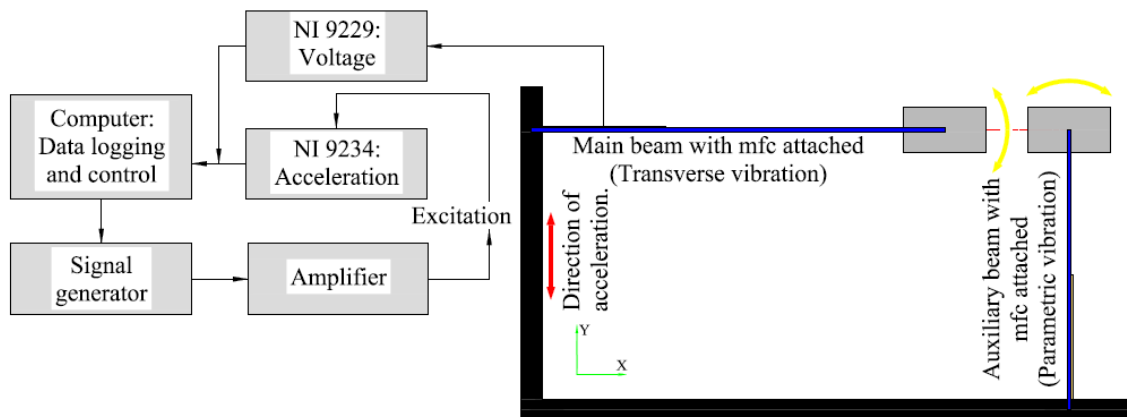


Figure 4. Layout of experimental setup

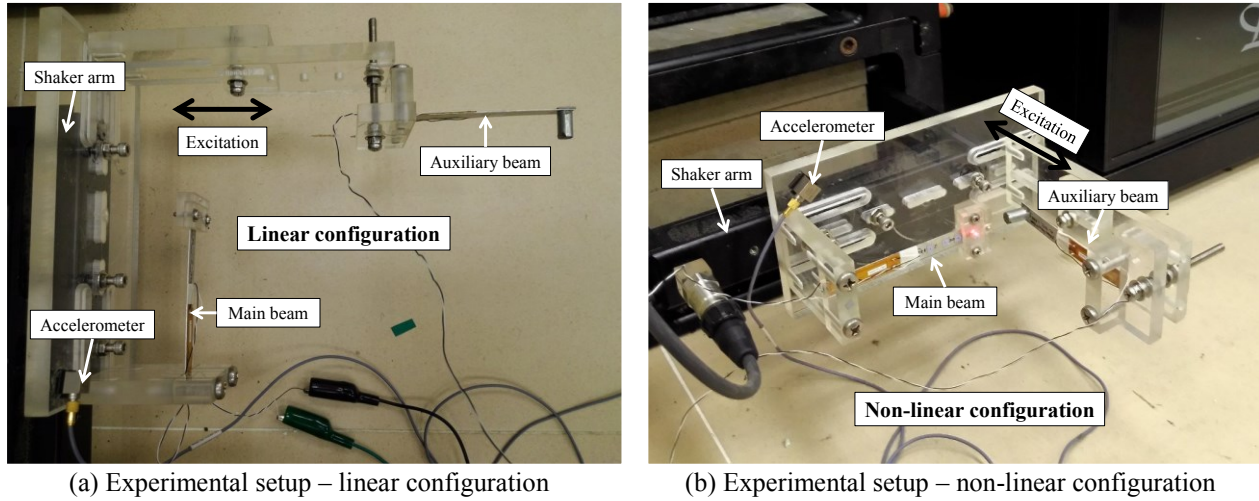


Figure 5. Experimental setup of the proposed system

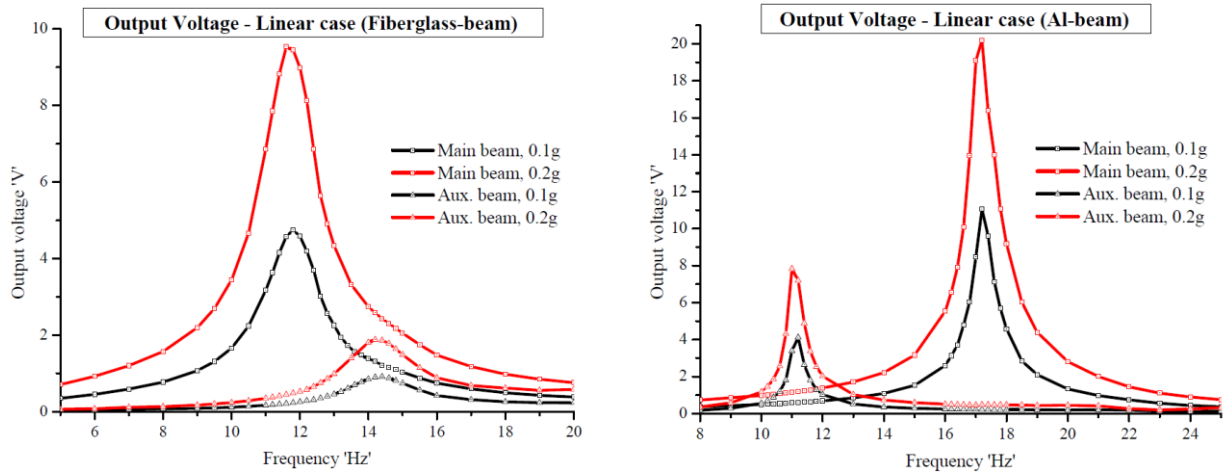
The PEH system was subject to external excitation with the help of a seismic shaker. The excitation of the shaker was controlled using a feedback mechanism, an accelerometer was used to monitor the excitation and send the signal back to the computer, the computer was connected to a signal generator and the necessary modifications to the drive signal were implemented from time to time and these were sent to the shaker through the shaker amplifier. Thus, the necessary level of sinusoidal excitation was monitored and maintained. During the course of the experiments, the whole system was subjected to a varying magnitude of excitation levels of 0.1g ($1g = 9.81m/s^2$) and 0.2g, within a frequency range of 5Hz to 50Hz. A total of two types of beam materials were tested (fiber glass and aluminum), the properties of the beams are displayed in table 1. For each set of beams, an initial setup consisting of a linear configuration was used followed by a nonlinear configuration with the magnets placed at a distance 'x' from each other under rest conditions and the magnets were tested for both attractive and repulsive configurations. The two types of beam materials were used to investigate the range of applicability of the proposed bandwidth enhancement method over different materials and configurations.

Table 1 Properties of the beams

Beam	Fiberglass	Aluminum	Tip mass	Magnet properties
Main beam	90mm x 10mm x 0.76mm	90mm x 10mm x 0.635mm	8.162g	NdFeB – N42, 8mm ϕ and 15mm thk
Auxiliary beam	90mm x 10mm x 0.76mm	90mm x 10mm x 0.4mm	6.865g	NdFeB – N35, 6mm ϕ and 2mm thk

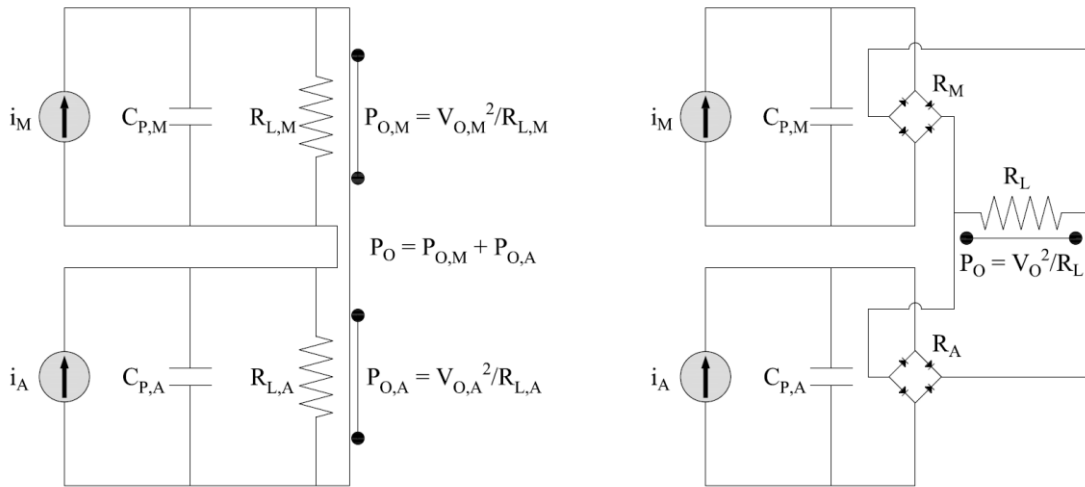
Experiments were performed by placing magnets at $x = 15mm$ and $x = 10mm$ apart, but the effect of nonlinearity wasn't so prominent at $x = 15mm$, so the results obtained from $x = 10mm$ are shown in this section. Fig. 6 displays the plots for output open circuit voltage (V_o) for a linear configuration of the system and the variation of the peaks of both main and auxiliary beams; it is interesting to note that in fiberglass beams the V_o peaks are much lower compared to that of the aluminum beams and the positioning of the peaks is much different, this is a direct indicator of the strain present in the beams for a same level of excitation. In fiberglass beams, as both the beams have similar cross section areas the peak for the auxiliary beam occurs at a higher frequency than the main beam, this supports the explanation about the primary parametric resonant frequency which occurs at about twice the first natural harmonic frequency [1,4,7]. Similarly, the presence of a thinner auxiliary aluminum beam results in a primary parametric resonant frequency which occurs at a lower frequency in comparison with the first harmonic

frequency of the main aluminum beam. Thus, the two configurations portray a qualitative experimental investigation of the behavior of the proposed design.



(a) Output open circuit voltage of a fiberglass beam (b) Output open circuit voltage of an aluminum beam
Figure 6. Plots for open circuit voltage of different beam in linear configuration

The primary improvement in the bandwidth from this design over that of the linear harvesters is illustrated using the power obtained from the system. Fig. 8 shows the various plots of output power (P_O) varying with frequency for various configurations of the system. Power was calculated from the open circuit voltage using the internal resistance of the voltage DAQ card (as this study is a preliminary proof of concept for the proposed design, the experimental determination of optimum resistance has been retained for future investigations). The circuit diagrams for the output power are shown in fig. 7, the piezoelectric part is shown as a parallel combination of a capacitor and a current source and the internal resistance for the voltage DAQ card ($R_{L,M}$, $R_{L,A}$, R_L) is placed parallel to the piezoelectric part [6]. The subscript 'M' is used for the main beam and 'A' for the auxiliary beam. When the beams were connected to different channels of the voltage card, the total power obtained is a summation of the power over individual channels. The variation of power was further probed by connecting single phase bridge rectifiers (R_M , R_A) to the piezoelectric part directly and the outputs from the rectifiers were connected in series before connecting it to the voltage DAQ card.



(a) Circuit diagram for direct power extraction (b) Circuit diagram for power extraction using rectifiers
Figure 7. Layout of experimental setup

The first two graphs on power distribution present a significant variation in the magnitude for the fiberglass and the aluminum beams. Secondly, the nonlinear behavior when magnets were placed in attractive configuration for the fiberglass beams provided an increased bandwidth at $10\mu\text{W}$ (about 10% of the peak) in comparison with the repulsive configuration; whereas, in the case of the aluminum beams the attractive configuration hardly provided any power as the magnets got stuck due to the flexible auxiliary beam. Moreover, in both the configurations the peak power output is slightly enhanced and the bandwidth is considerably increased by more than 100% at a level of 10% the peak P_O in all cases. The aluminum beams were further investigated by attaching rectifiers, there is almost 20% drop in the peak power due to the presence of rectifiers, yet a similar trend in enhancement of the peak power and shift in resonant frequencies for both the main and auxiliary beams was observed. Moreover, the bandwidth and the average power (area under the curve) are also enhanced; the presence of two resonant frequencies close to each other and the effect of internal resonance have been discussed in the literature [3], this is the fundamental reason for the enhancement of the bandwidth using the proposed design. The major drawback from the usage of the rectifiers for the aluminum beams is attributed to the cancellation and interference from the main and auxiliary beams, thus there is a considerable dip in between both the peaks, this can be overcome by extracting power from both the beams separately by using energy harvesting circuitry and summing them up at the end. These aspects of the experimental investigations will be considered for detailed analysis in the future works.

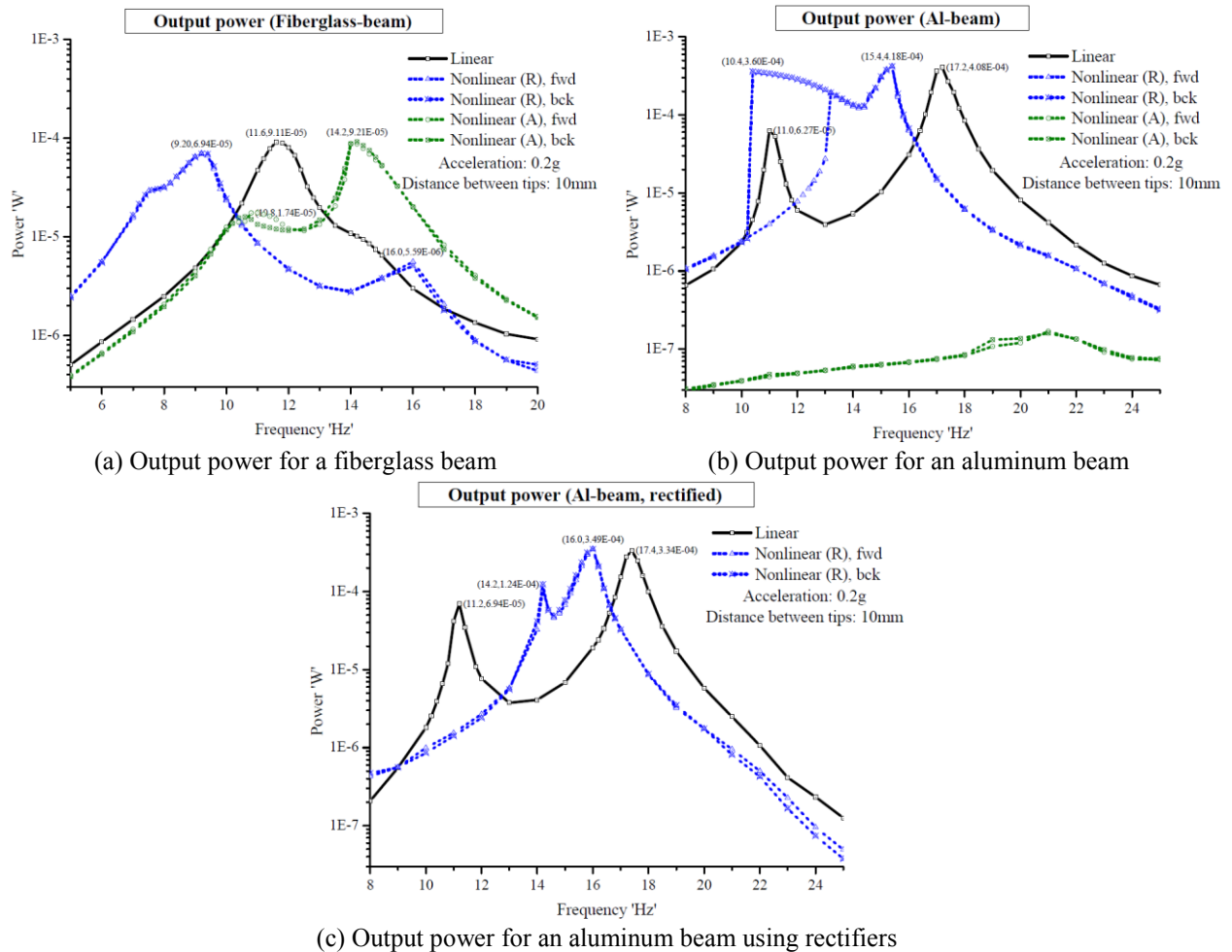


Figure 8. Plots for output power of the beams in both linear and nonlinear configurations

5. CONCLUSIONS

The present study illustrates a contemporary design for a PEH system which consists of two flexural members undergoing transverse and parametric vibrations respectively, and are coupled together using magnets. Piezoelectric MFC transducers are attached to both the beams and the resonant frequencies of the beams complement each other with the added nonlinearity from the magnets to give an enhanced bandwidth of the output power distribution. Moreover, in comparison with a linear case the nonlinear configuration has a relatively higher peak and a higher average power distribution too. A qualitative experimental analysis was performed by testing two types of beam material, resulting in parametric resonant peaks on either side of the resonant peaks obtained for the main beams. It was observed that the aluminum beams produce higher output voltage and output power due to the higher modulus of elasticity and the aluminum beams are more effective for a repulsive configuration of magnets, and the fiberglass beams are more effective for an attractive case. In short, the effectiveness of the configuration of magnets can be determined depending on the stiffness of the main and auxiliary beams and their corresponding natural and parametric resonant frequencies. The connections for the output voltage and power were also investigated; on rectification of the output voltage from the beams, though there is increment in the bandwidth by about 100% the peaks drop by about 20% and the bandwidth decreases in comparison with the non-rectified case. Thus, for a PEH system consisting of two or more sources of power, a circuit configuration to derive power separately is more advantageous than combining the sources directly. Further, the harvesters can be optimally tuned to perform efficiently when the direction of excitation is interchanged, this can be achieved in a system where the natural harmonics of the vibrating members are close enough to cause internal resonance between two different modes of vibration. In the present study, the fiberglass beams with closer natural harmonics and coupled magnetic interactions are more suitable for such interchange of directions; the aluminum beams need appropriate tuning for such a scenario.

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